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# Coefficient of Variation Spectral Analysis: An Application to Underwater Acoustics

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### **Preface**

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20. Continued:

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from contaminating components. The theory of the  $C_V$  is presented. Coefficients for several classical input distributions are developed. It is shown that  $C_V$  spectra can be easily implemented as an adjunct procedure during the computation of the ensemble of averaged power spectra. Power and  $C_V$  spectra derived from actual at-sea sonobuoy measurements of deep ocean ambient noise are shown. Whereas, it is virtually impossible to separate narrowband contaminating components from narrowband lines of interest in the ensemble of averaged power spectra, these acoustic components of interest can be distinguished in the  $C_V$  spectra.

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**Coefficient of Variation Spectral Analysis:  
An Application to Underwater Acoustics**

Power spectral analysis using the fast Fourier transform (FFT) has become a routine method for the detection of narrowband components of interest in broadband data. Unfortunately, numerous contaminating narrowband components of no interest are often present.

## **NARROWBAND ANALYSIS OF UNDERWATER ACOUSTIC DATA**

- **INFORMATION OF INTEREST**
- **CONTAMINATING COMPONENTS**

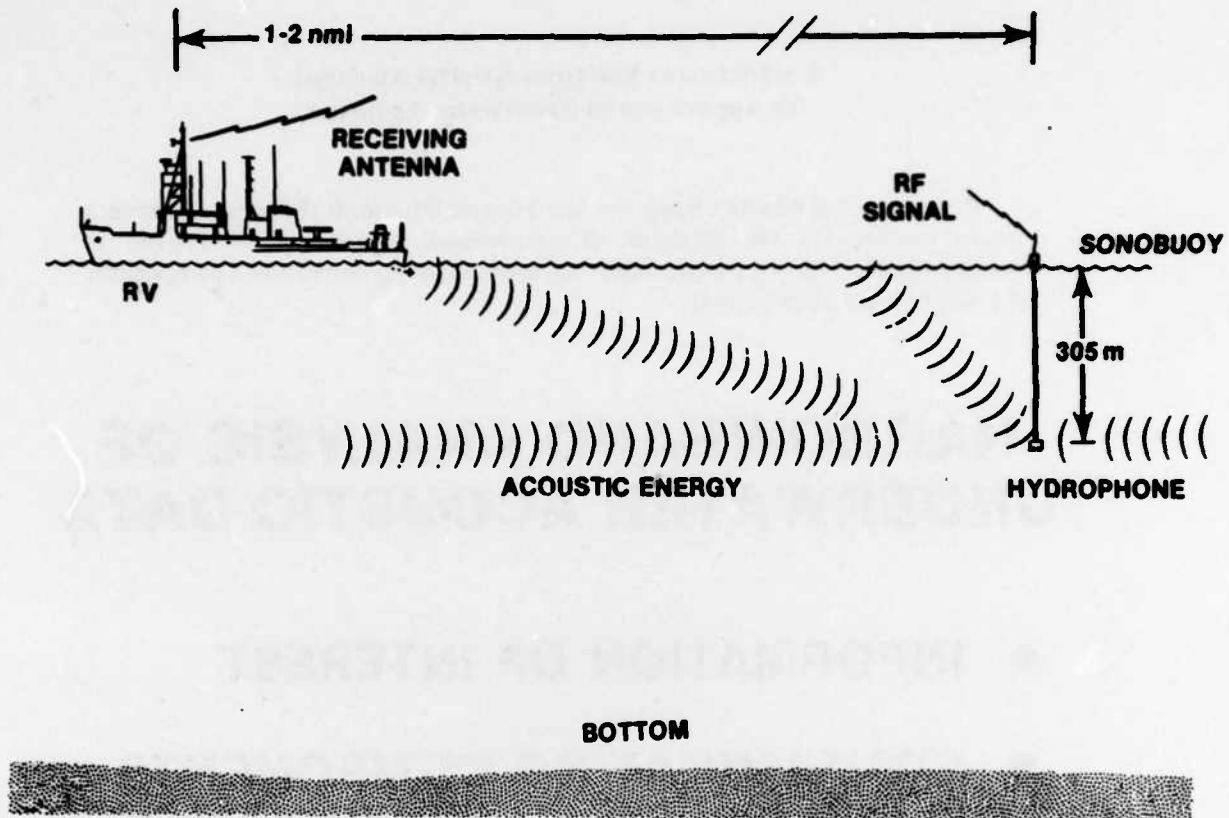
**Slide 1**

Today, we will examine the use of the coefficient of variation ( $C_V$ ) spectrum as an adjunct to the conventional power spectrum to distinguish narrowband components of interest from the contaminating components. First, we will present a problem in underwater acoustics requiring the identification of narrowband components of interest in the presence of numerous contaminating components. Next, the mathematics of the  $C_V$  spectrum will be defined. The  $C_V$  spectrum will be developed for several types of input processes. Finally, results obtained from at-sea measurements will be examined.



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## ACOUSTIC EXPERIMENT



Slide 2

As an example of the problem, consider an experiment designed to measure the narrowband components of the acoustic energy radiated by a research vessel. To conduct this experiment, a sonobuoy is deployed 1 to 2 nmi from the research vessel. Acoustic energy (radiating from the ship's machinery, propellers, etc.) travels underwater to the sonobuoy's underwater microphone. The acoustic data are then telemetered back to the research vessel via a radio frequency link where the data are recorded on magnetic tape. As can be seen in this slide, acoustic energy from directions other than the research vessel is also arriving at the sonobuoy. As the open ocean is a noisy environment, this energy could contain narrowband components generated by distant ships or other sources. However, the only information of interest is the acoustic energy emanating from the research vessel. When the sonobuoy data are played back for power spectral analysis, additional narrowband contaminants (such as, ac line voltage interference and tape recorder artifacts) can also be introduced. Consider the situation when there is no *a priori* information about the number and frequencies of the narrowband components associated with the research vessel's acoustic energy. It would then be extremely difficult to identify these components from all the other contributing narrowband components observed in the power spectrum of the sonobuoy data.



## **POWER SPECTRUM ANALYSIS**

- **MAGNITUDE SQUARED PROCESS**
- **CLASSIFICATION BY SNR**
- **BANDWIDTH/FLUCTUATION LIMITATIONS**

### **Slide 3**

The problem is that power spectral analysis provides enough information to distinguish narrowband components from broadband data, but not enough information to distinguish the narrowband information of interest from the contaminants. Since power spectral estimation is essentially a magnitude squared process, narrowband components are distinguished from broadband components by the observation that the level associated with a particular FFT bin is higher than the level in adjacent bins. Calling the contents of these nearby bins "noise," one can detect narrowband components in the noise by use of a signal-to-noise threshold. Any narrowband line, regardless of source, will be classified as a narrowband component if it exceeds the specified signal-to-noise ratio (SNR).

In order to obtain a smooth estimate of the broadband components, individual power spectra are often averaged to provide an ensemble of averaged power spectra. Unless the FFT resolution is sufficiently narrow, it is impossible to determine from the ensembled averaged spectra whether the power level of the narrowband component was constant over the ensemble estimate or varied significantly from spectrum to spectrum. Yet, this information could serve as an additional classification tool.

## **MOMENT CHARACTERIZATION OF SPECTRAL DATA**

- **ENSEMBLE OF SPECTRAL ESTIMATES**
- **CHARACTERIZE BY STANDARD DEVIATION TO MEAN RATIO**
- **WEAKLY FLUCTUATING PROCESSES WILL HAVE LOW RATIOS**
- **HIGHLY FLUCTUATING PROCESSES WILL HAVE HIGH RATIOS**

### **Slide 4**

Consider statistical moment characterization of spectral estimates. If the ensemble of spectral estimates is thought of as a sequence of power values, then the statistical moments of that sequence can be computed. In fact, the ensemble of averaged spectra is the first moment, or mean, of the sequence. If the second moment is computed, then the standard deviation of the sequence can be derived. The standard deviation provides a measure of the fluctuation of the sequence. If the standard deviation is divided by the mean, this normalized measure of the fluctuations is called the  $C_V$  (coefficient of variation). A sequence of narrowband power spectral values with a standard deviation less than the mean will have a  $C_V$  of less than one. Conversely, a sequence with a standard deviation greater than the mean will have a  $C_V$  greater than one.



## COEFFICIENT OF VARIATION SPECTRUM

1)  $G(f)$  = TRUE SPECTRAL DENSITY

2)  $\hat{G}(f)$  = ESTIMATED SPECTRAL DENSITY

$$3) C_V(f) = \frac{\sqrt{E[\hat{G}(f)^2] - E^2[\hat{G}(f)]}}{G(f)}$$

$$4) C_V(f) = \frac{\sigma(\hat{G}(f))}{G(f)}$$

$$5) \hat{C}_V(f) = \frac{\sigma(\hat{G}(f))}{E[\hat{G}(f)]}$$

Slide 5

The  $C_V$  spectrum can be developed as follows. Equation 1 defines  $G$  as the true power spectral density of an input process. It is a function of frequency. In equation 2,  $\hat{G}$  is the *estimated* spectral density. The  $C_V$  is then defined as a ratio given in equation 3. The numerator is the square root of the difference between the estimated power spectral density's second moment and first moment squared. The denominator is the true power spectral density. The  $C_V$  can be more simply defined, in equation 4, as the ratio of the standard deviation of the estimated power density to the true spectral density. In actual practice, the true spectral density is seldom known. Thus, we must use an estimate of equation 4. As shown in equation 5, the estimated coefficient of variation ( $\hat{C}_V$ ) is now purely in terms of the estimated power spectral density.

## ESTIMATION OF $C_V(f)$

CONSIDER AN  $N$  ELEMENT ENSEMBLE OF  $\hat{G}(f)$

$$6) \hat{G}_i(f) \quad i = 1, 2, \dots, N$$

$$7) E(\hat{G}(f)) = \frac{1}{N} \sum_{i=1}^N \hat{G}_i(f)$$

$$8) \sigma(\hat{G}(f)) = \left[ \left( \frac{1}{N-1} \right) \sum_{i=1}^N (\hat{G}_i(f) - E(\hat{G}(f)))^2 \right]^{1/2}$$

$$9) \sigma(\hat{G}(f)) = \left[ \left( \frac{1}{N-1} \right) \left( \sum_{i=1}^N \hat{G}_i^2(f) - 2E(\hat{G}(f)) \sum_{i=1}^N \hat{G}_i(f) + E^2(\hat{G}(f)) N \right) \right]^{1/2}$$

$$10) \hat{C}_V(f) = \frac{\sigma(\hat{G}(f))}{E(\hat{G}(f))}$$

### Slide 6

The  $\hat{C}_V$  can be readily computed provided that the individual elements,  $\hat{G}_i$ , comprising the ensemble of  $N$  spectral estimates are available, as defined in equation 6. In equation 7, the first moment of the ensemble is computed. This result is the ensemble of averaged power densities. Equation 8 defines the estimate of the unbiased standard deviation. Equation 9, an expansion of equation 8, is shown because the computer implementation of this form of the standard deviation can be accomplished without using matrices. The ratio of equation 9 to equation 7 is the  $\hat{C}_V$  spectrum, as shown in equation 10. Since  $\hat{C}_V$  is so dependent on the ensemble of averaged power spectral densities, it is important to choose a sufficiently large value of  $N$  so that the ensemble averaged power is a good estimate of the true power. However,  $N$  should be less than the value that would make the sequence of spectral estimates nonstationary.

## COEFFICIENT OF VARIATION FOR GAUSSIAN INPUT

$$11) G_X(f) = 2 \lim_{T \rightarrow \infty} \frac{1}{T} E[|X(f, T)|^2]$$

$$12) \hat{G}_X(f, T) = \frac{2}{T} (X_R^2(f, T) + X_I^2(f, T))$$

$$13) C_V(f) = \frac{\sigma(\hat{G}(f))}{G(f)}$$

$$14) C_V(f) = \frac{\sqrt{2n}}{n} ; n = 2$$

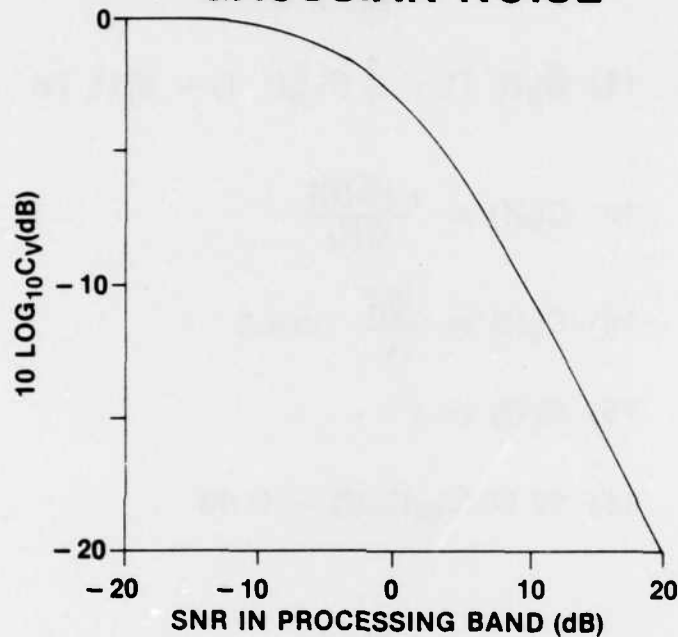
$$15) C_V(f) = 1$$

$$16) 10 \text{ LOG}_{10} C_V(f) = 0 \text{ dB}$$

### Slide 7

Consider an acoustic sequence called  $X$  that is Gaussian with zero mean. Its true spectral density is arbitrary, but can be strongly frequency dependent. Equation 11 presents the classical definition of the power spectral density, where  $X$  is the Fourier transform of the pressure sequence. Recall that the Fourier transform of a Gaussian process is Gaussian. The variable  $T$  is integration time. Equation 12 defines the estimated power density as the sum of the squares at the real and imaginary terms. Thus,  $G$  has a Chi-squared distribution of order 2. The  $C_V$  is the ratio in equation 13. Equation 14 presents the ratio for the general case of  $n$  degrees of freedom. When  $n=2$ , the  $C_V$  reduces to a value of 1. The corresponding logarithmic result is 0 dB. Note that this result is independent of frequency. Thus, regardless of the power spectral density associated with the input signal, as long as the input has a Gaussian distribution, it will have a true  $C_V$  value of 1, independent of frequency.

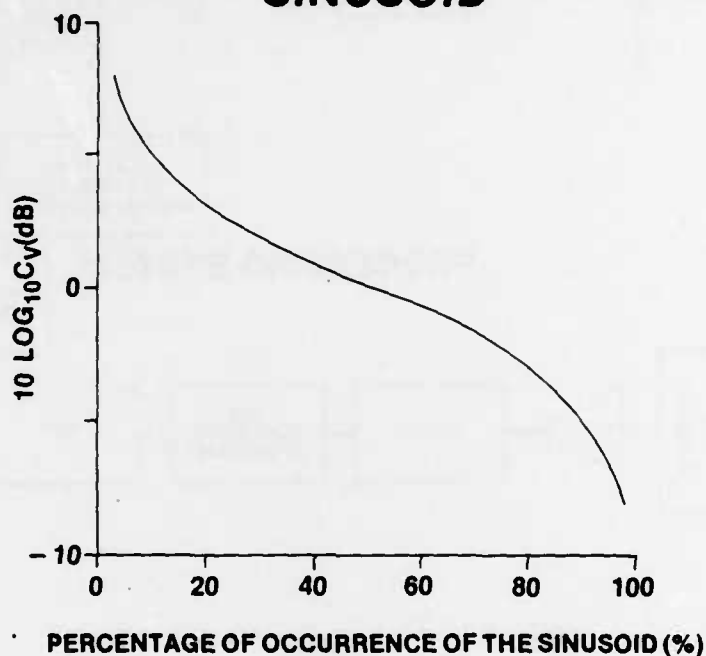
## $C_V$ FOR SPECTRAL LEVEL OF DATA CONTAINING A SINUSOID IN GAUSSIAN NOISE



### Slide 8

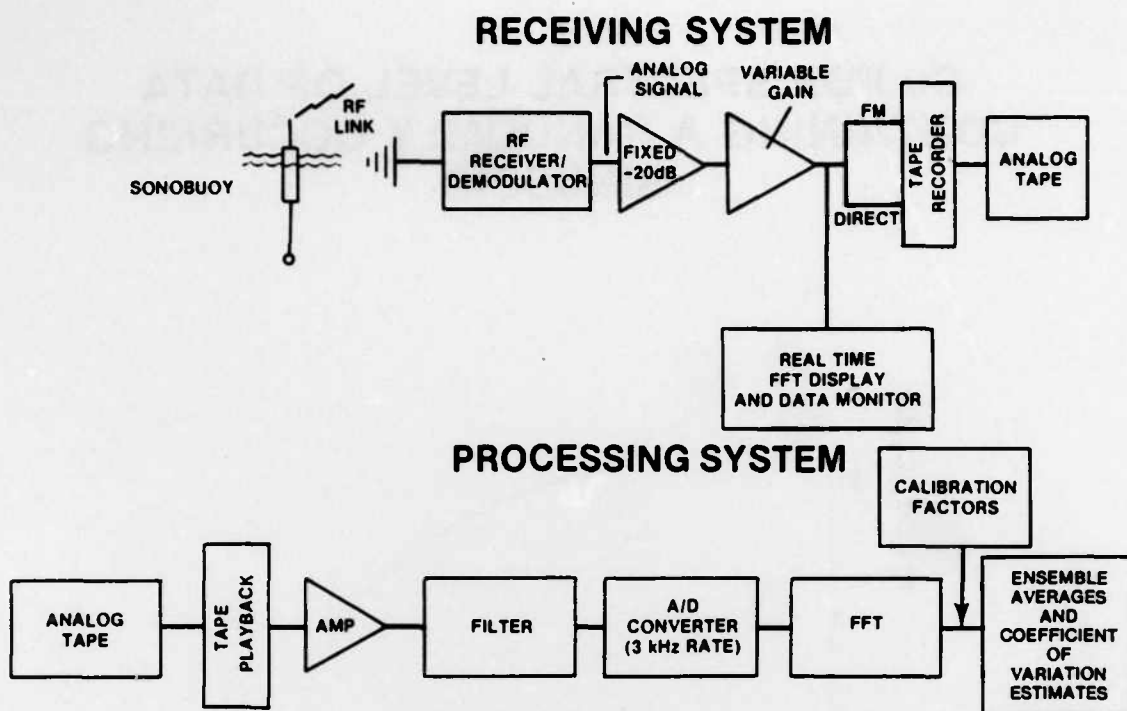
Now, consider a more complicated pressure sequence consisting of a sinusoidal signal of *fixed* amplitude in the presence of zero mean Gaussian noise. Consider the  $C_V$  in dB space as a function of SNR. Note that for very low SNR,  $C_V$  is 0 dB. This is consistent with the previous result of 0 dB for a purely Gaussian input. As the SNR increases,  $C_V$  decreases. This is intuitively logical, since the power spectrum of a sinusoid of constant level will itself be constant; hence, its second moment will be zero, and the resulting logarithmic  $C_V$  will be minus infinity.

## **$C_V$ FOR SPECTRAL LEVEL OF DATA CONTAINING A RANDOMLY OCCURRING SINUSOID**



### **Slide 9**

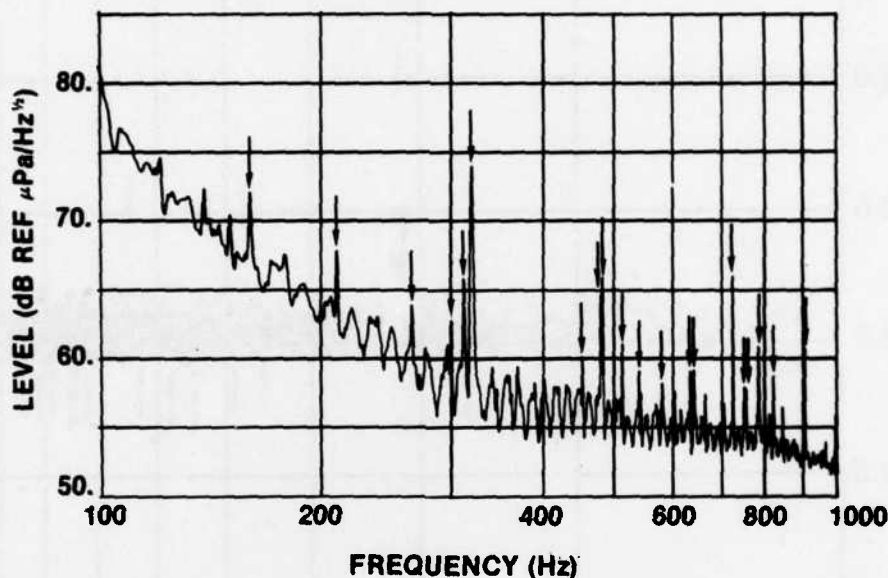
In the previous example,  $C_V$  could never be greater than 0 dB, since the standard deviation of the power density was always less than the mean. Now, consider a sequence in which a sinusoid is occurring a specified percentage of the time, and the remaining percentage is reduced to zero level input. As can be seen, when the occurrence of the sinusoid is less than 50 percent,  $C_V$  will be greater than 0 dB. As the percentage of occurrence of the sine wave increases,  $C_V$  decreases. Again, this is intuitively logical since when the sinusoid is occurring 100 percent of the time, the  $C_V$  will be minus infinity dB, i.e., infinitely small in linear space.



## Slide 10

Now consider  $C_V$  applied to a set of measured underwater acoustic data. Recall the experiment described earlier. The goal of that experiment was to measure the narrowband components of the acoustic energy radiated by a research vessel. To accomplish this, a sonobuoy containing a hydrophone was deployed and operated at about 1 to 2 nmi from the vessel. Shown in the upper portion of this slide is a block diagram of the receiving system onboard the research vessel. The telemetered data were demodulated, amplified, and recorded on tape. The data were also monitored with a real time FFT power spectrum analyzer. When this exercise was conducted, many more narrowband lines were observed than originally anticipated. After the sea-test, the data were then processed as shown in the lower portion of this slide. Data from the analog tapes were filtered, A/D converted, and then FFT analyzed. Both ensemble of averaged power spectra and  $C_V$  spectra were computed.

# POWER SPECTRUM SONOBUOY UNDERWATER ACOUSTIC DATA 5 MIN AVG, 1.1 Hz RESOLUTION

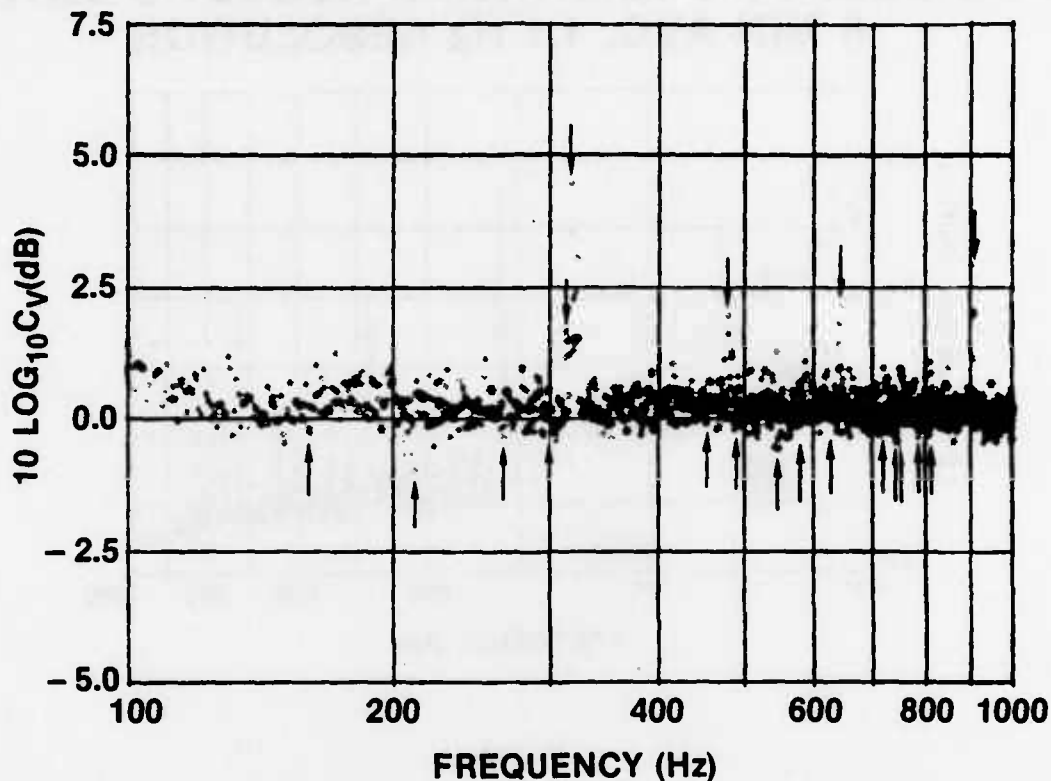


Slide 11

Here is the ensemble of averaged power spectra for 5 minutes of received data. It was computed from Hanning weighted 50 percent overlapped input records. The effective resolution is 1.1 Hz. Although somewhat difficult to see, note the numerous narrowband components rising above a broadband background that decreases as frequency increases. The arrows indicate the narrowband components that were at least 3 dB above the broadband background. Could some or all of these components have been generated by the research vessel?



## COEFFICIENT OF VARIATION SPECTRUM SONOBUOY UNDERWATER ACOUSTIC DATA 5 MIN AVG, 1.1 Hz RESOLUTION



Slide 12

This is the  $C_V$  spectrum derived from the same spectra used to compute the ensemble of averaged power spectra just shown. Striking differences can be seen. First, the broadband background now is essentially independent of frequency. Second, the number of observable narrowband components has been drastically reduced. The arrows indicate the narrowband components identified in the previous slide. Only five lines are observable above approximately 2 dB, and no lines are observed below -2 dB. How can these results be interpreted?

Recall that the logarithmic  $C_V$  of a Gaussian process is 0 dB. This is true whether the process is narrowband or broadband. Thus, those lines previously observable in the power spectrum, but not observable here, may actually be narrowband Gaussian processes. Distant narrowband lines of near constant source level can be amplitude modulated by the ocean. If this modulation is Gaussian-like, then it would be expected that distant source narrowband components would have  $C_V$  on the order of 0 dB, regardless of power spectral level.

What about the five lines with large positive coefficients? Recall the case of a sinusoid randomly occurring a given percentage of the time. During the 5 minutes this data were acquired, the research vessel's engines were being constantly adjusted in an attempt to station keep. In fact, a separate examination of  $C_V$  in the frequency regime of 20-30 Hz, where ship's propeller energy is expected, showed  $C_V$  values greater than 3 dB. Thus, it is very likely that all five lines shown here are associated with the research vessel. The observation that there are no  $C_V$  values less than -2 dB is also significant. Based on the model of a constant amplitude sinusoid in the presence of Gaussian noise, when the SNR is greater than 0 dB, corresponding  $C_V$  values should be less than -3 dB. The absence of any substantially negative  $C_V$  values would seem to preclude any constant level sinusoids in the data, such as 60 hz and related harmonic contamination.

## **COEFFICIENT OF VARIATION SPECTRAL ANALYSIS SUMMARY**

- **USEFUL TECHNIQUE FOR CHARACTERIZATION  
BY STATISTICAL PROCESS**
- **ADJUNCT TO POWER SPECTRAL ANALYSIS,  
REQUIRING SLIGHTLY ADDITIONAL PROCESSING  
AND MEMORY**
- **ESPECIALLY APPROPRIATE TO UNDERWATER  
ACOUSTICS DUE TO EXPECTED FLUCTUATIONS  
RELATED TO THE OCEAN ENVIRONMENT**

### **Slide 13**

We have examined the use of  $C_V$  spectral analysis. The  $C_V$  is the ratio of the standard deviation of the power spectral density to the mean. It is a technique for characterizing a process by its statistical behavior. It is a useful adjunct to conventional FFT power spectral analysis, since additional information is gained with only slightly additional processing and memory required. Finally, this technique, appropriate in underwater acoustics due to inherent ocean environment fluctuations, should be equally appropriate to other acoustic environments also containing fluctuating narrowband components.

Thank you. Are there any questions?

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